Program of Métodos Matemáticos de la Especialidad (Técnicas Energéticas)

Chapter 1 Lagrange polynomial interpolation in 1D

1.1) Introduction.
1.2) Definition of Lagrange interpolation polynomial.
1.3) Matrix method to calculate the interpolation polynomial.
1.4) Lagrange interpolation formula.
1.5) Lagrange bases.
1.6) Newton formula of Lagrange polynomial.
1.7) Divided differences.
1.8) Some properties of divided differences.
1.9) Error of polynomial interpolation.
1.10) Pros and cons of polynomial interpolation.
1.11) Chebyshev points as good points for polynomial interpolation.

Chapter 2 Hermite interpolation

2.1) Introduction.
2.2) Definition of Hermite interpolation polynomial.
2.3) Matrix method to calculate the Hermite interpolation polynomial.
2.4) Hermite polynomial in terms of Lagrange bases.
24) Hermite polynomial and divided differences
2.5) The interpolation error.

Chapter 3 Finite element interpolation in 1D

3.1) Introduction: Why piecewise interpolation?
3.2) Partition of the finite interval $I \subset \mathbb{R}$: nodes, elements and features of a good mesh.
3.3) Storage of mesh data.
3.4) Lagrange and Hermite formulas of the piecewise interpolation polynomial in a generic element.
3.5) Finite element spaces.
3.6) Local a global bases.
3.7) Global representation of the piecewise interpolation polynomial.
3.8) Element of reference and bijective transformations.
3.9) The finite element interpolation error.

Chapter 4 Lagrange finite element interpolation in 2D

4.1) Introduction.
4.2) Admissible meshes
4.3) Storage of mesh data.
4.4) Lagrange interpolation in a triangle
4.5) Lagrange interpolation in a rectangle.
4.6) The reference element.

4.7) Affine and isoparametric transformations.
4.8) Finite element spaces.
4.9) Local and global bases.
4.10) The interpolation error.

Chapter 5 Numerical calculation of definite integrals
5.1) Introduction.
5.2) Definition and properties of a quadrature rule.
5.3) Some simple but useful quadrature rules in 1D.
5.4) Generation of quadrature rules in 1D: Newton-Cotes rules.
5.5) Gaussian quadrature in 1D.
5.7) The error of quadrature rules in 1D.
5.6) Composed quadrature.
5.8) Some quadrature rules for triangles and squares.

Chapter 6 Functional setting for linear partial differential equations
6.1) Multidimensional integration by parts.
6.2) Weak derivatives.
6.3) Introduction to functional spaces L^2, H^m, $m \geq 1$.

Chapter 7 Second order linear elliptic problems
7.1) Definition of second order linear elliptic problems.
7.2) Engineering examples.
7.3) Definition of the classical solution:Examples.
7.4) Definition of the weak solution: Why the weak solution is the right solution in engineering problems?
*7.5) Bilinear form and linear functional associated with the weak solution.
*7.6) Existence and uniqueness of the weak solution.

Chapter 8 Finite element solution of second order elliptic problems
8.1) Construction of finite element spaces.
8.2) Finite element formulation.
8.3) Matrix formulation of the finite element solution.
8.4) Case study 1: step by step of the numerical solution of a one-dimensional elliptic problem.
*8.5) Case study 2: step by step of the numerical solution of a two-dimensional elliptic problem.
*8.6) Error analysis.

Chapter 9 Evolution problems I: linear parabolic problems
9.1) The parabolic model problem.
9.2) Definition of the classical solution: examples.
9.3) Definition of the weak solution and study of its more important properties.

9.4) Time discretization by the implicit and explicit Euler schemes and Crank-Nicolson scheme.

9.5) Finite element formulation of the time discretized problem.

9.6) Stability of the numerical solution.

9.7) Case study 1: step by step of the numerical solution of a one-dimnesional parabolic problem.

*9.8) Case study 2: step by step of the numerical solution of a two-dimensional parabolic problem.

Chapter 10 Evolution problems II: second order hyperbolic problems

10.1) The second order wave equation.

10.2) Time discretization of the second order wave equation: explicit schemes and Newmark scheme

10.3) Finte element solution of the time discretized equation.

10.4) Stability of the numerical solution.

10.5) Case study 1: step by step of the numerical solution of one dimensional wave equation.

***Chapter 11 Elliptic eigenvalue problem**

11.1) Eigenfunction expansions.

11.2) Finite element solution of an elliptic eigenvalue problem.

***Chapter 12 Introduction to the numerical solution of inverse problems**

12.1) Introduction to inverse problems.

12.2) A simple one-dimensional linear problem.

12.3) Inverse problems with time independent parameters.